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Delay-based Congestion Control for Low Latency

David Hayes <davihay@ifi.uio.no>

David Ros <David.Ros@telecom-bretagne.eu>

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Delay Measures

Measures:

- ▶ T_{RTT}
- ▶ T_{OWD}
- ▶ usually interested in T_q , but requires T_{RTT_min} or T_{OWD_min}
- ▶ but with multi-path T_{OWD} or T_{RTT} maybe just as important as T_q
- ▶ gradient or change in delay
- ▶ ...

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Coexistence?

Loss based (LB) congestion control and delay based (DB) congestion control do not coexist well

- ▶ LB tries to fill the queues
- ▶ DB tries to keeps them small

Hybrid two-state methods

- ▶ only reduces delay in the long term
 - ▶ (as loss based flows disappear)
 - ▶ long term is still important!

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Why should we use delay-based congestion control?

The delay signal is:

- ▶ A measure of the quantity we are trying to reduce
- ▶ A fundamental characteristic of packet switched networks
 - ▶ requires no special signal
- ▶ May also aid in using available capacity more quickly

Ideally:

- ▶ A measurement based CC that tries to keep latency low

∴ congestion control for low latency,

SHOULD include delay as **A** congestion measure.

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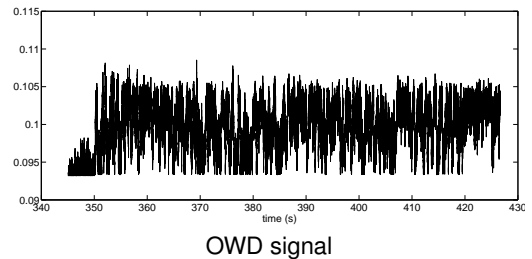
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Why is delay a difficult signal to use?



Dealing with Noise:

- ▶ Reverse path (RTT)
- ▶ Raw / probabilistic – collective behaviour matters
- ▶ Filtering: mean, median, exponential, kalman

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A way forward

Delay based CC for:

- ▶ homogeneous systems (e.g. data centres)
- ▶ Scavenger class traffic
- ▶ small buffers
- ▶ incentives for deploying DBCC
 - ▶ perhaps policing
 - ▶ isolation of delay-based flows
- ▶ in combination with other signals (such as ECN)

DBCC is not **THE** solution, but should be **PART** of the solution

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